

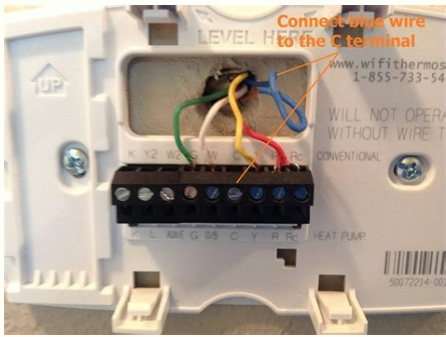
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Petros Ioannou is a Professor in the Department of Electrical Engineering - Systems and Director of the Center of Advanced Transportation Technologies at the University of Southern California, Los Angeles. The stability proofs are often long and technical and possibly distracting to readers who prefer to focus on the design and implementation of adaptive control. Appropriate for Masters and PhD-level students as well as engineers and mathematicians. You're Reading a Free Preview Page 140 is not shown in this preview. You're Reading a Free Preview Pages 311 to 322 are not shown in this preview. His research interests include adaptive and nonlinear control, switching and hybrid systems, autonomous formations, sensor networks, mechatronics, and various control applications, including high-performance and hypersonic flight control, semiconductor manufacturing process control, and disk-drive servo systems. You're Reading a Free Preview Pages 17 to 57 are not shown in this preview. Ioannou is the author or coauthor of eight books and over 200 research papers. Fidan Chapter 2: Parametric Models [PDF 191 KB] Chapter 3: Parameter Identification: Continuous Time [PDF 558 KB] Chapter 4: Parameter Identification: Discrete Time [PDF 489 KB] Chapter 5: Continuous-Time Model Reference Adaptive Control [PDF 656 KB] Chapter 6: Continuous-Time Adaptive Pole Placement Control [PDF 375 KB] Chapter 7: Adaptive Control for Discrete-Time Systems [PDF 779 KB] Appendix [PDF 310 KB] F16 Materials Read Me [PDF 208KB] Conditions of Use [PDF 10KB] Model [PDF 1.68MB] M-files [Zip 38KB] Donate · Contact Us · Site Map · Join SIAM · My Account Balances rigour with practice. You're Reading a Free Preview Pages 357 to 362 are not shown in this preview. His research interests include adaptive control, neural networks, nonlinear systems, vehicle dynamics and control, intelligent transportation systems, and marine transportation. Baris Fidan is a researcher at the Systems Engineering and Complex Systems Program of National ICT Australia and the Research School of Information Sciences and Engineering of the Australian National University in Canberra. You're Reading a Free Preview Pages 382 to 399 are not shown in this preview. Presents the design, analysis, and application of a variety of algorithms used to manage dynamical systems with unknown parameters. You're Reading a Free Preview Pages 230 to 250 are not shown in this preview. You're Reading a Free Preview Pages 366 to 369 are not shown in this preview. P. You're Reading a Free Preview Pages 88 to 112 are not shown in this preview. He also holds a courtesy appointment with USC's Department of Aerospace and Mechanical Engineering. You're Reading a Free Preview Pages 259 to 289 are not shown in this preview. You're Reading a Free Preview Pages 331 to 345 are not shown in this preview. For this reason we are placing the extensive and complicated proofs on this Web site so readers interested in the theory of adaptive control can access them. The inclusion of these proofs makes the book complete in its treatment of adaptive control. Also supplementing each chapter are additional examples that use the adaptive control toolbox. Putting them on this site enables us to further enrich the tutorial nature of the book and keep the book a reasonable length. Online examples are available, as is a solutions manual for teachers. Presents the design, analysis, and application of algorithms for managing dynamical systems with unknown parameters. You're Reading a Free Preview Pages 377 to 378 are not shown in this preview. Adaptive control systems are time varying and nonlinear, thus more challenging to analyze and understand than traditional linear time invariant controllers. Ioannou B. You're Reading a Free Preview Page 373 is not shown in this preview. You're Reading a Free Preview Pages 146 to 158 are not shown in this preview. You're Reading a Free Preview Pages 162 to 187 are not shown in this preview. You're Reading a Free Preview Pages 199 to 204 are not shown in this preview. You're Reading a Free Preview Pages 298 to 302 are not shown in this preview. You're Reading a Free Preview Pages 208 to 213 are not shown in this preview. You're Reading a Free Preview Pages 66 to 79 are not shown in this preview. This book will be useful to masters- and Ph.D.-level students as well as electrical, mechanical, and aerospace engineers and applied mathematicians.

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